Knowledge Discovery in Large-Scale Batch Processes through Explainable Boosted Models and Uncertainty Quantification: Application to Rubber



Quantification: Application to Rubber Mixing

35th European Symposium on Computer Aided Process Engineering (ESCAPE)

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1. Introduction

1.1 Rubber Mixing Production Line

Rubber mixing (RM): **crucial process** where raw rubber is combined with various additives. Such additives have distinct properties to achieve desired tire performance.

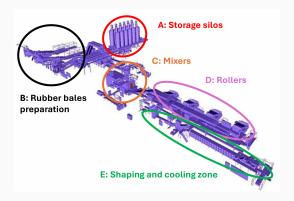


Figure 1: 3D Representation of a monostep Michelin mixing line [1]

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- lack of insights into the underlying physical process.
- neglect of key process variables for the model.
- the lack of uncertainty quantification (UQ) providing reliability.

1.3 The Proposed Data-Driven Approach

To overcome the aforementioned **challenges** in RM, we propose a data-driven framework that:

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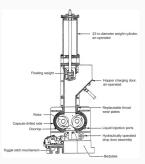
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- Employs novel feature selection and explainability to analyze process-quality relationships.
- Incorporates critical process variables, including material properties, environmental conditions . . .
- Delivers trustworthy predictions through conformal prediction (CP) methods.

2. Case Study

2.1 Rubber Mixing Process

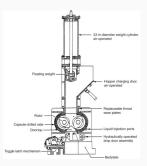
Figure 2: Banbury mixer diagram [8]



Thermomechanical processing occurs in the mixer. The entire mixing process requires about 1 hour to complete.

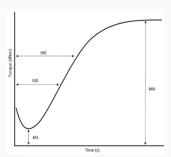
2.1 Rubber Mixing Process

Figure 2: Banbury mixer diagram [8]



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Figure 3: Rheological curve [9]



At the end of the process, the sub-quality (y) is measured through heating and shear tests to assess rheological properties [9], [10].

2.2 Data Representation — Output Sub-quality

After collecting the sub-quality data, we can build a tabular dataset *D*.

D with n = 35,525 samples and d = 316 features.

$$D = \{(X, y) \mid X \in \mathbb{R}^{n \times d}, \ y \in \mathbb{R}^n\}$$

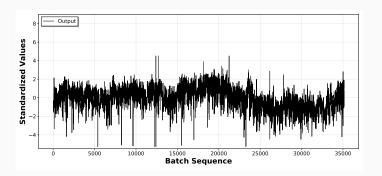


Figure 4: Evolution of the output sub-quality over time

Process states (PS): physical properties related to the machines (e.g. mixer's internal pressure or rotor rotation speed) through 99 features.

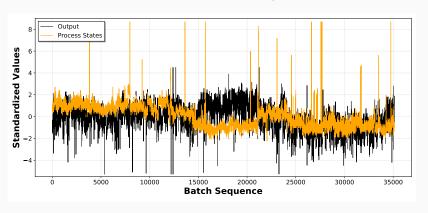


Figure 5: Evolution of one process state variable over time

Raw material quality (RMQ): properties of the input materials (e.g. black carbon content) through 37 features.

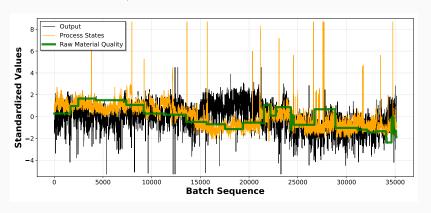


Figure 5: Evolution of one raw material quality variable over time

Wheather conditions (WC): environmental conditions (e.g. ambient temperature or humidity) through 22 features.

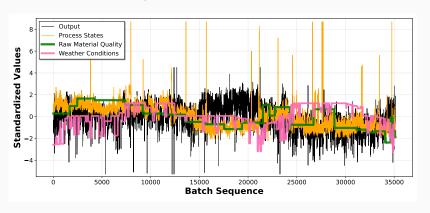


Figure 5: Evolution of one wheather condition variable over time

Context: global and temporal information (e.g. campaign information) via 4 features.

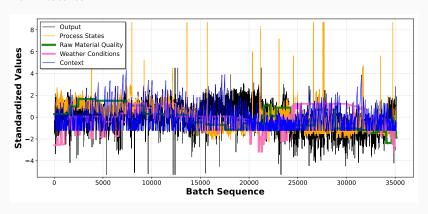


Figure 5: Evolution of one context variable over time

Production recipe settings (PRS): parameters controlling the production process (e.g. machines' settings) through 154 features.

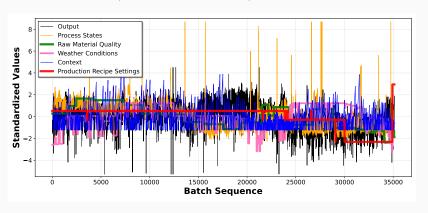
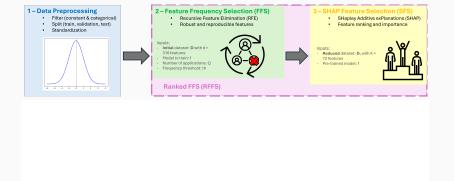


Figure 5: Evolution of one production recipe settings variable over time [1]

3. Methodology

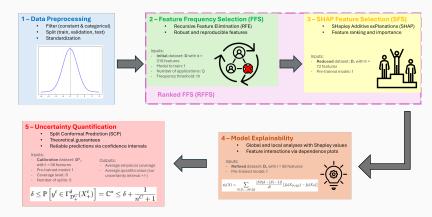
3.1 An Explainable and Reliable Data-Driven Framework

Figure 6: A Framework for Offline Explainable and Reliable Monitoring.



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3.2 Ranked Feature Frequency Selection

Ranked Feature Frequency Selection (RFFS) is a two-step feature selection method based on:

1. Feature Frequency Selection (FFS): Multiple feature selection via recursive feature elimination (RFE) procedure [11], [12].

3.2 Ranked Feature Frequency Selection

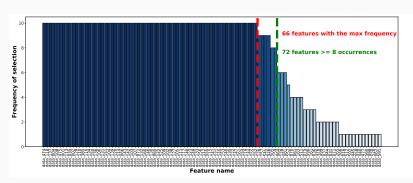
Ranked Feature Frequency Selection (RFFS) is a two-step feature selection method based on:

- 1. Feature Frequency Selection (FFS): Multiple feature selection via recursive feature elimination (RFE) procedure [11], [12].
- 2. SHAP Feature Selection (SFS): Feature contribution and ranking via SHAP values [13], [14].

4. Results

4.1 Frequency-based Feature Selection

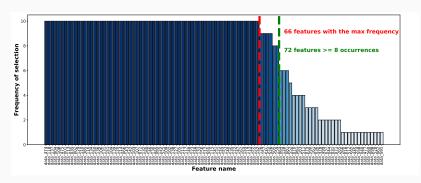
Figure 7: Feature frequency selection (FFS) histogram with 10 runs [1].



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4.1 Frequency-based Feature Selection

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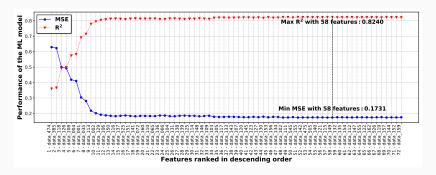


Across 10 runs: 104 unique features; 66 in all runs, and 72 in at least 80% of runs. These 72 robust and reproducible features constitute the reduced dataset D_* .

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4.1 SHAP-based Feature Selection

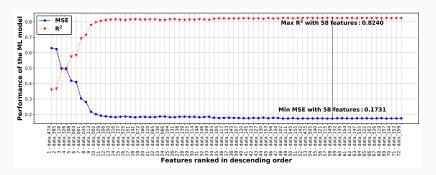
Figure 8: SHAP feature selection (SFS) validation.



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4.1 SHAP-based Feature Selection

Figure 8: SHAP feature selection (SFS) validation.



Across the 72 feature combinations, the best performance is achieved with 58 features. These 58 ranked features are used to build the refined dataset D_+ .

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4.2 Predictive Performance

Table 1: Comparison of ML model performance at each step of the method: (i) initial dataset D with d=316 features, (ii) reduced dataset D_* with K=72 features, and (iii) further refined dataset D_+ with $\ell=58$ features.

Dataset used for model development	ML model performance		Improvement relative to baseline (%)		
	MSE	R ²	MSE	R^2	No. of features
D (d = 316)	0.209	0.788	/	/	/
$D_* (K = 72)$	0.174	0.824	17%	4.6%	77%
$D_{+} (\ell = 58)$	0.173	0.824	17%	4.6%	82%

Results 12/17

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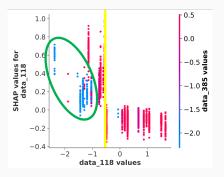
The two-stage process is effective, via (i) a feature reduction by 82% and (ii) a predictive performance improvement with a MSE drop of 17% and a R^2 score increase of 4.6%.

A more parsimonious model leads to better results.

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4.3 Model Explainability

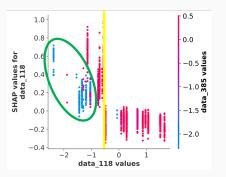
Figure 9: SHAP dependency plot (DP) between data_118 and data_385.



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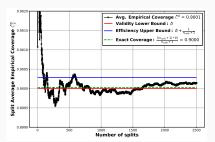
- 1. data_118 below -0.75 boosts predictions, while higher values dampen them.
- 2. Low data_385 values occur only when data_118 is less than -1, indicating a synergistic interaction.

It outlines how explainability can uncover hidden feature interactions.

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4.4 Uncertainty Quantification

Figure 10: SCP convergence graph of the average empirical coverage $\bar{\mathbb{C}}^{\delta}$.

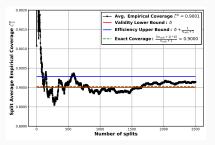


The statistical properties of CP are satisfied: the average empirical coverage $\bar{\mathbb{C}}^{\delta}$ converges to the true coverage \mathbb{C}^* .

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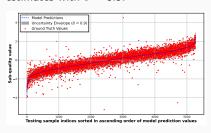
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Figure 11: SCP testing uncertainty estimates with $\delta = 0.9$.



SCP builds a constant uncertainty estimate with a **testing coverage** C^t of 0.9009. Also, it maintains narrow confidence intervals.

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5. Conclusion

5.1 Summary

Through feature selection (RFFS), explainability (SHAP), and uncertainty quantification (SCP), our approach delivers benefits across operational domains:

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Reduced testing costs and time (seconds vs. hours) by (i) prediction accuracy enhancement (17% for the MSE) and (ii) trustworthy uncertainty estimates (90% confidence interval) with theoretical guarantees. It enables targeted and efficient laboratory sampling.

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5.1 Summary

Through feature selection (RFFS), explainability (SHAP), and uncertainty quantification (SCP), our approach delivers benefits across operational domains:

- Reduced testing costs and time (seconds vs. hours) by (i) prediction accuracy enhancement (17% for the MSE) and (ii) trustworthy uncertainty estimates (90% confidence interval) with theoretical guarantees. It enables targeted and efficient laboratory sampling.
- Streamlined process management by identifying key variables (58 features with a 82% reduction) and providing interpretable insights. It enables engineers to simplify and optimize control strategies.

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- Continuous monitoring with adaptive uncertainty quantification in a live manufacturing environment will be enabled by a transition to online quality monitoring.

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Thank you for your attention! Questions?

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- Contributors: Eric Moulines, Sylvain Desroziers, Guillaume Ramelet

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FFS Algorithm [1]

Algorithm 1: Frequency Feature Selection (FFS)

```
Input: Training set D^T = \left\{ (X^T, y^T) \mid X^T \in \mathbb{R}^{n^T \times d}, y^T \in \mathbb{R}^{n^T \times 1} \right\}, Feature selection method RFE, Model to train f_\theta, Number of applications Q, Frequency threshold th, for q \in \{1, \dots, Q\} do
\begin{bmatrix} \text{Randomly sample a subset } D_q^T \subset D^T; \\ \text{Train } f_\theta^q \text{ on } D_q^T; \\ \text{Apply RFE on } f_\theta^q \text{ to select features } x_q^T \in \mathbb{R}^{d_q}; \\ \text{Compute the frequency apparition of each feature: } F = \text{freq}(\left\{x_q^T\right\}_{q=0}^Q); \\ \text{Retrieve only the valid features: } x_+^T = \left\{x_j \mid F(x_j) \geq th\right\}; \\ \text{return } Dataset \text{ with } valid \text{ features } D_* = \left\{(X_*, y) \mid X_* \in \mathbb{R}^{n \times k}, y \in \mathbb{R}^{n \times 1}\right\}
```

SFS Algorithm [1]

Algorithm 5: SHAP Feature Selection (SFS)

Input: Training set $D_*^T = \left\{ (X_*^T, y^T) \mid X_*^T \in \mathbb{R}^{n^T \times k}, y^T \in \mathbb{R}^{n^T \times 1} \right\}$, Trained model f_{θ}^* ,

for feature $x_j \in x_*^T$ do

Calculate Shapley value $\phi_j(X_*^T)$

for feature $x_j \in x_*^T$ do

Calculate global importance index $I_j(X_*^T) = \overline{|\phi_j(X_*^T)|}$

Rank $I = \{I_j\}_{j=0}^d$ in descending order and reorder x_*^T accordingly:

$$x_*^T = \{x_1, x_2, \dots, x_l, \dots, x_k\}^T$$

where x_r represents the r-th most important feature;

for feature $x_j \in x_*^T$ do

Train a new model f_{θ}^{j} using the top j features:

$$\hat{y} = f_{\theta}^{j}(X_{j}^{T})$$

where $X_j^T = \{x_1, ..., x_j\};$

Evaluate model performance;

Identify the smallest subset X_+ where adding more features does not improve predictive performance;

return Dataset with best features $D_+ = \{(X_+, y) \mid X_+ \in \mathbb{R}^{n \times l}, y \in \mathbb{R}^{n \times 1}\}$

SCP Algorithm [1]

Algorithm 7: Split Conformal Prediction (SCP)

Input: Calibration set $D_+^C = \{(X_+^C, y^C) \mid X_+^C \in \mathbb{R}^{n^C \times l}, y^C \in \mathbb{R}^{n^C \times 1} \}$, coverage level δ , number of splits S, trained model f_θ^+

for $split s \in \{1, \dots, S\}$ do

Shuffle $D_{+}^{\dot{C}}$;

Split D_+^C into a sub-calibration set $D_{+,s}^{SC}=(X_+^{SC},y_+^{SC})_s$ and a validation set $D_{+,s}^V=(X_+^V,y_+^V)_s$;

Predict sub-calibration outputs $\hat{y}_s^{SC} = f_{\theta}^+(X_+^{SC});$ Compute non-conformity scores $\mathcal{A}_s = |\hat{y}_s^{SC} - y_s^{SC}|;$

Compute non-conformity scores $A_s = |y_s| - y_s$

Calculate the quantile value $Q_s^{\delta} = \text{quantile}(A_s, \delta);$

Calculate prediction intervals for each validation point $i \in \{1, ..., n^V\}$ with $n^V = |D_+^V|$:

$$\Gamma_{D_{+,s}^{SC}}^{\delta,s}(X_{i,s}^V) = \{\hat{y}_{i,s}^V \pm Q_s^\delta\} \quad \forall i$$

Compute the split empirical coverage:

$$\mathbb{C}_{\Gamma^{\delta,s}_{D^{S,C}_{+,s}}}(D^{V}_{+,s}) = \frac{1}{n^{V}} \sum_{i=1}^{n^{V}} \mathbb{I}_{[y^{V}_{i,s} \in \Gamma^{\delta,s}_{D^{S,C}_{+,s}}(X^{V}_{i,s})]}$$

Compute the split average empirical coverage:

$$\bar{\mathbb{C}}_{s}^{\delta} = \frac{1}{s} \sum_{k=1}^{s} \mathbb{C}_{\Gamma_{D_{+,s}}^{\delta,k}}$$

Compute average empirical coverage and average quantile value across all splits:

$$\bar{\mathbb{C}}^{\delta} = \frac{1}{S} \sum_{s=1}^{S} \bar{\mathbb{C}}_{s}^{\delta}$$
, and $\bar{Q}^{\delta} = \frac{1}{S} \sum_{s=1}^{S} Q_{s}^{\delta}$

return Average empirical coverage $\bar{\mathbb{C}}^{\delta}$, Average quantile value \bar{Q}^{δ}

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